## Solution Problem 1

a) Calculation of the velocity at the instant before impact

Equating the potential gravitational energy to the kinetic energy at the instant before impact we can arrive at the pre-impact velocity $v_{0}$ :

$$
\begin{equation*}
m g h=\frac{m v_{0}^{2}}{2} \tag{1}
\end{equation*}
$$

from which we may solve for $v_{0}$ as follows:

$$
\begin{equation*}
V_{0}=\sqrt{2 g h} \tag{2}
\end{equation*}
$$

b) Calculation of the vertical component of the velocity at the instant after impact

Let $v_{2 x}$ and $v_{2 y}$ be the horizontal and vertical components, respectively, of the velocity of the mass center an instant after impact. The height attained in the vertical direction will be $\alpha h$ and then:
$v_{2 y}^{2}=2 g \alpha h$
from which, in terms of $\alpha$ (or the restitution coefficient $c=\sqrt{\alpha}$ ):
$v_{2 y}=\sqrt{2 \mathrm{~g} \alpha \mathrm{~h}}=c v_{0}$
c) General equations for the variations of linear and angular momenta in the time interval of the Impact

Figure 1.2 shows the free body of the ball during impact


Considering that the linear impulse of the forces is equal to the variation of the linear momentum and that the angular impulse of the torques is equal to the variation of the angular momentum, we have:

$$
\begin{align*}
I_{y} & =\int_{t_{1}}^{t_{2}} N(t) d t=m v_{0}+m v_{2 y}=m(1+c) \sqrt{2 g h}  \tag{5}\\
I_{x} & =\int_{t_{1}}^{t_{2}} f_{r}(t) d t=m v_{2 x} \tag{6}
\end{align*}
$$

$$
\begin{equation*}
I_{\theta}=\int_{t_{1}}^{t_{2}} R f_{r}(t) d t=R \int_{t_{1}}^{t_{2}} f_{r}(t) d t=\mathrm{I}\left(\omega_{o}-\omega_{2}\right) \tag{7}
\end{equation*}
$$

Where $I_{x}, I_{y}$ and $I_{\theta}$ are the linear and angular impulses of the acting forces and $\omega_{2}$ is the angular velocity after impact. The times $t_{l}$ and $t_{2}$ correspond to the beginning and end of impact.

## Variants

At the beginning of the impact the ball will always be sliding because it has a certain angular velocity $\omega_{0}$. There are, then, two possibilities:
I. The entire impact takes place without the friction being able to spin the ball enough for it to stop at the contact point and go into pure rolling motion.
II. For a certain time $t \in\left(t_{1}, t_{2}\right)$, the point that comes into contact with the floor has a velocity equal to zero and from that moment the friction is zero. Let us look at each case independently.

Case I
In this variant, during the entire moment of impact, the ball is sliding and the friction relates to the normal force as:
$f_{r}=\mu_{k} N(t)$
Substituting (8) in relations (6) and (7), and using (5), we find that:

$$
\begin{equation*}
\mathrm{I}_{\mathrm{x}}=\mu_{k} \int_{t_{1}}^{t_{2}} N(t) d t=\mu_{k} \mathrm{I}_{\mathrm{y}}=\mu_{k}(1+c) \sqrt{2 g h}=m v_{2 x} \tag{9}
\end{equation*}
$$

and:

$$
\begin{equation*}
\mathrm{I}_{\theta}=\mathrm{R} \mu_{k} \int_{t_{1}}^{t_{1}} N(t) d t=\mathrm{R} \mu_{k} m(1+c) \sqrt{2 g h}=\mathrm{I}\left(\mu_{0}-\mu_{2}\right) \tag{10}
\end{equation*}
$$

which can give us the horizontal component of the velocity $v_{2 x}$ and the final angular velocity in the form:

$$
\begin{align*}
& V_{2 x}=\mu_{k}(1+c) \sqrt{2 g h}  \tag{11}\\
& \omega_{2}=\omega_{0}-\frac{\mu_{k} m R(1+c)}{I} \sqrt{2 g h} \tag{12}
\end{align*}
$$

With this we have all the basic magnitudes in terms of data. The range of validity of the solution under consideration may be obtained from (11) and (12). This solution will be valid whenever at the end of the impact the contact point has a velocity in the direction of the negative $x$. That is, if:

$$
\begin{align*}
& \omega_{2} \mathrm{R}>v_{2 x} \\
& \omega_{0}-\frac{\mu_{k} m R(1+c)}{I} \sqrt{2 g h}>\frac{\mu_{k}(1+c)}{R} \sqrt{2 g h} \\
& \omega_{0}>\frac{\mu_{k} \sqrt{2 g h}}{R}(1+c)\left(\frac{m R^{2}}{I}+1\right) \tag{13}
\end{align*}
$$

so, for angular velocities below this value, the solution is not valid.
Case II
In this case, rolling is attained for a time $t$ between the initial time $t_{1}$ and the final time $t_{2}$ of the impact. Then the following relationship should exist between the horizontal component of the velocity $v_{2 x}$ and the final angular velocity:
$\omega_{2} \mathrm{R}=v_{2 x}$
Substituting (14) and (6) in (7), we get that:

$$
\begin{equation*}
m \mathrm{R} v_{2 x}=\mathrm{I}\left(\omega_{0}-\frac{v_{2 x}}{R}\right) \tag{15}
\end{equation*}
$$

which can be solved for the final values:

$$
\begin{equation*}
V_{2 x}=\frac{I \omega_{0}}{m R+\frac{I}{R}}=\frac{I \omega_{0} R}{m R^{2}+I}=\frac{2}{7} \omega_{0} \mathrm{R} \tag{16}
\end{equation*}
$$

and:

$$
\begin{equation*}
\omega_{2}=\frac{I \omega_{0}}{m R^{2}+I}=\frac{2}{7} \omega_{0} \tag{17}
\end{equation*}
$$

## Calculation of the tangents of the angles

Case I
For $\tan \theta$ we have, from (4) and (11), that:

$$
\begin{align*}
& \tan \theta=\frac{v_{2 x}}{v_{2 y}}=\frac{\mu_{k}(1+c) \sqrt{2 g h}}{c \sqrt{2 g h}}=\mu_{k} \frac{(1+c)}{c} \\
& \tan \theta=\mu_{k} \frac{(1+c)}{c} \tag{18}
\end{align*}
$$

i.e., the angle is independent of $\omega_{0}$.

Case II
Here (4) and (16) determine for $\tan \theta$ that:

$$
\begin{align*}
\tan \theta & =\frac{v_{2 x}}{v_{2 y}}=\frac{I \omega_{0} R}{I+m R^{2}} \frac{1}{c \sqrt{2 g h}}=\frac{I \omega_{0} R}{\left(I+m R^{2}\right) c \sqrt{2 g h}} \\
\tan \theta & =\frac{2 \omega_{0} R}{7 c \sqrt{2 g h}} \tag{19}
\end{align*}
$$

then (18) and (19) give the solution (fig. 1.3).


Figure 1.3
We see that $\theta$ does not depend on $\omega_{\mathrm{o}}$ if $\omega_{0}>\omega_{0 \text { min }}$; where $\omega_{0 \text { min }}$ is given as:

$$
\omega_{\mathrm{o} \text { min }}=\frac{\mu_{k}(1+c) \sqrt{2 g h}\left(1+\frac{m R^{2}}{I}\right)}{R}
$$

$$
\begin{equation*}
\omega_{\mathrm{o} \min }=\frac{7 \mu_{k}(1+c) \sqrt{2 g h}}{2 R} \tag{20}
\end{equation*}
$$

Calculation of the distance to the second point of impact
Case I
The rising and falling time of the ball is:

$$
\begin{equation*}
\mathrm{t}_{v}=2 \frac{v_{2 y}}{g}=\frac{2 c \sqrt{2 g h}}{g}=2 c \sqrt{\frac{2 h}{g}} \tag{21}
\end{equation*}
$$

The distance to be found, then, is;

$$
\begin{align*}
& \quad d_{I}=v_{2 x} t_{v}=\mu_{k}(1+c) \sqrt{2 g h} 2 c \sqrt{\frac{2 h}{g}} \\
& \begin{array}{c}
d_{l}=4 \mu_{\mathrm{k}}(1+c) c h \\
\text { which is independent of } \omega_{0} .
\end{array} \tag{22}
\end{align*}
$$

## Case II

In this case, the rising and falling time of the ball will be the one given in (21). Thus the distance we are trying to find may be calculated by multiplying $t_{v}$ by the velocity $v_{2 x}$ so that:

$$
\begin{aligned}
d_{I I} & =v_{2 x} t_{v}=\frac{I \omega_{0}}{m R^{2}+I} 2 c \sqrt{\frac{2 h}{g}}=\frac{2 \omega_{0} R c}{1+\frac{5}{2}} \sqrt{\frac{2 h}{g}} \\
d_{I I} & =\frac{4}{7} c \sqrt{\frac{2 h}{g}} R \omega_{0}
\end{aligned}
$$

Thus, the distance to the second point of impact of the ball increases linearly with $\omega_{0}$.

## Marking Code

The point value of each of the sections is:

$$
\begin{array}{ll}
\text { 1.a } & 2 \text { points } \\
\text { 1.b } & 1.5 \text { points } \\
\text { 1.c } & 2 \text { points } \\
& \\
\text { 2.a } & 2 \text { points } \\
\text { 2.b } & 1.5 \text { points } \\
3 & 1 \text { point }
\end{array}
$$

